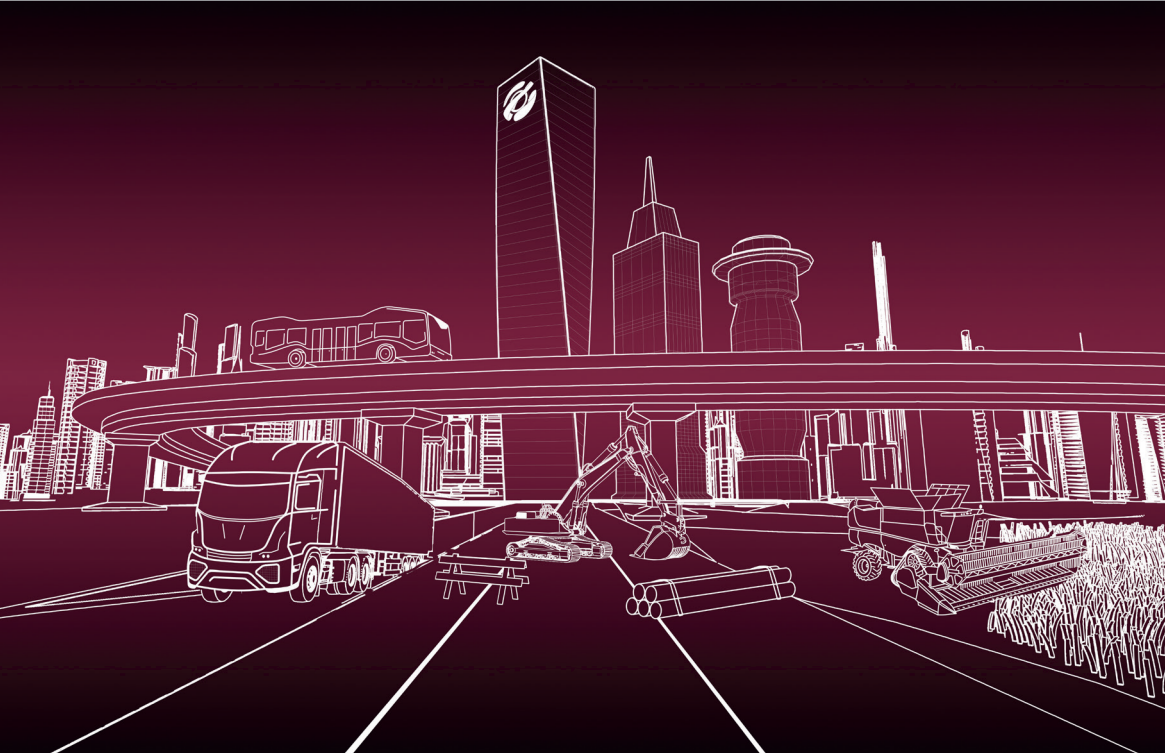


# PROGRAM OVERVIEW



## 8<sup>th</sup> International Commercial Vehicle Technology Symposium Kaiserslautern

March 13-14, 2024  
University Kaiserslautern-Landau



**commercial vehicle alliance**  
kaiserslautern

version: November 07, 2023

# PROGRAM OVERVIEW

Wednesday, march 13, 2024

9:00	<b>Opening and welcome</b> <b>Keynote</b>	room 115
10:00	<b>Exhibition and Coffee break</b>	lobby
10:45	<b>Simulation Methods (1)</b> <i>Presentations see page 4</i>	room 110
	<b>Alternative propulsion technologies (1)</b> <i>Presentations see page 4</i>	room 115
12:00	<b>Exhibitor presentation</b>	lobby
12:45	<b>Lunch break</b>	lobby
13:45	<b>Safety, Reliability and Durability</b> <i>Presentations see page 4</i>	room 110
	<b>Connected and integrated systems and services</b> <i>Presentations see page 4</i>	room 115
15:30	<b>Vehicle presentation</b>	lobby
16:15	<b>Exhibition and Coffee break</b>	lobby
16:45	<b>Innovative Development and Production Methods (1)</b> <i>Presentations see page 5</i>	room 115
19:00	<b>Conference dinner</b>	city

# PROGRAM OVERVIEW

Thursday, March 14, 2024

8:30	<b>Welcome &amp; Review</b>	room 115
8:45	<b>Assisted and Automated Driving and Working</b> <i>Presentations see page 5</i>	room 115
10:00	<b>Exhibition, Poster presentation and Coffee break</b>	lobby
11:00	<b>Simulation Methods (2)</b> <i>Presentations see page 5</i>	room 110
	<b>Innovative Development and Production Methods (2)</b> <i>Presentations see page 5</i>	room 115
12:15	<b>Exhibition and Lunch break</b>	lobby
13:45	<b>Alternative propulsion technologies (2)</b> <i>Presentations see page 5</i>	room 115
15:00	<b>Final plenary session</b>	room 115

# PRESENTATIONS

Wednesday, march 13, 2024

SIMULATION METHODS (1)		room 110
10.45	AI-based Surrogate Modeling for Highly Efficient Soil-Tool Simulation	Emmerich; Harutyunyan; Steidel; Burger (Fraunhofer ITWM)
-	Efficient HiL-Test Generation for Electric Heavy-Duty Drivetrains using Model-Based Systems Engineering	Mennicken (RWTH Aachen)
12.00	Cascading of feasible tyre characteristics of tyre design specifications using a tyre resizing tool	Lidberg <sup>1</sup> ; Li <sup>2</sup> ( <sup>1</sup> Fraunhofer Chalmers Centre; <sup>2</sup> Volvo Cars Corporation)

ALTERNATIVE PROPULSION TECHNOLOGIES (1)		room 115
10.45	Potenziale und Herausforderungen wasserstoffbetriebener Baumaschinen	Trommler; Hänel; Will (TU Dresden)
-	Energieeffiziente und verschleißoptimierte Betriebsstrategien für Sonder- und Nutzfahrzeuge mit Brennstoffzellenantrieb	Ufert; Singaravelan; Steinert (Fraunhofer IVI)
12.00	Mercedes-Benz eCitaro fuel cell: mehr Reichweite ohne Nachladen dank Brennstoffzelle	Javed (Daimler Buses)

SAFETY, RELIABILITY AND DURABILITY		room 110
13.45	Dynamic Risk Assessment for Automated Driving System using Artificial Neural Network	Patel <sup>1</sup> ; Gorasiya <sup>2</sup> ; Liggesmeyer <sup>1,2</sup> ( <sup>1</sup> RPTU Kaiserslautern-Landau; <sup>2</sup> Fraunhofer IESE)
-	Extended Language Server Support for Robotics Frameworks	Klaaßen; Meckel; Berns (RPTU Kaiserslautern-Landau)
15.30	Active perception and monitoring of data quality to increase the sensing performance of autonomous off-road robots	Wolf <sup>1</sup> ; Berns <sup>2</sup> ( <sup>1</sup> Fraunhofer IESE; <sup>2</sup> RPTU Kaiserslautern-Landau)
	Tree-SLAM: Localization and Mapping in Dense Forest Environments for Autonomous Vehicles	Heupel <sup>1</sup> ; Wolf <sup>2</sup> ; Berns <sup>1</sup> ( <sup>1</sup> RPTU Kaiserslautern-Landau; <sup>2</sup> Fraunhofer IESE)

CONNECTED AND INTEGRATED SYSTEMS AND SERVICES		room 115
13.45	Prediction of energy consumption in road transport by simulation of the vehicle's field of application and its performance	Biedinger; Christiansen; Dahlheimer; Halfmann; Speckert; Wagner (Fraunhofer ITWM)
-	AI-based vehicle activity recognition using telemetry data	Burger <sup>1</sup> ; Fiedler <sup>1</sup> ; Jansen <sup>2</sup> ; Kickert <sup>2</sup> ; Kleeberg <sup>2</sup> ; Philipp <sup>2</sup> ( <sup>1</sup> Fraunhofer ITWM; <sup>2</sup> Volvo CE)
15.30	The (important) Role of Digital Twins and AI Methods within Predictive Maintenance Strategies	Baur; Teutsch (RPTU Kaiserslautern-Landau)
	Open APIs in the era of the software-defined commercial vehicle	Tanimov; Achtzehn; Stumpf; Henkel; Muenzenmay (Robert Bosch)

Wednesday, march 13, 2024 & Thursday, march 14, 2023

## INNOVATIVE DEVELOPMENT AND PRODUCTION METHODS (1)

room 115

16.45	Multidisciplinary design optimization of electric truck motors with additively manufactured hairpin winding	Umland <sup>1</sup> ; Winkler <sup>2</sup> ; Kutter <sup>2</sup> ; Jung <sup>3</sup> ( <sup>1</sup> Fraunhofer IFAM; <sup>2</sup> BPW Bergische Achsen; <sup>3</sup> Additive Drives)
-	Konstruktionsmethodische Synthese der additiven Fertigung und des Tailored-Fiber-Placements zur Lasteinleitung in FKV-Bauteile	Rupp <sup>1</sup> ; Al-Zuhairi <sup>1</sup> ; Teutsch <sup>2</sup> ; Nagaraj <sup>2</sup> ; Pfaff <sup>2</sup> ; Motsch <sup>2</sup> ; Digel <sup>3</sup> ( <sup>1</sup> RPTU Kaiserslautern-Landau; <sup>2</sup> Leibniz-Institut für Verbundwerkstoffe; <sup>3</sup> Digel Sticktech
18.00	Simulation and testing of Hybrid Load-bearing Structures for Lightweight Construction in Vehicles	Nagaraj (Leibniz-Institut für Verbundwerkstoffe)

## ASSISTED AND AUTOMATED DRIVING AND WORKING

room 115

08.45	Fahrerassistenz und Teleoperation, technische Lösungen als Antwort auf Marktanforderungen	Hofmann (Liebherr Hydraulikbagger)
-	Full Virtual Workflow to support Automation & Autonomy Applications for Commercial Vehicles including AI	Eichhorn <sup>1</sup> ; Höh <sup>1</sup> ; Gumaste <sup>2</sup> ; Vaidya <sup>2</sup> ( <sup>1</sup> John Deere ETIC; <sup>2</sup> John Deere India)
10.00	Kollisionsverhinderungssystem für schemelgelenkte Tandemwalzen	Telschow (BOMAG)

## SIMULATION METHODS (2)

room 110

11.00	Effiziente Entwicklungsprozesse für optimale Nutzfahrzeug-Antriebslösungen durch durchgängigen Einsatz skalierbarer Simulationsmodelle	Scherpelz; Baumann; Horn; Glücker (ZF Friedrichshafen)
-	Cloud-Based Identification of Dynamic Trailer States	Burger <sup>1</sup> ; Hoffeld <sup>1</sup> ; Steidel <sup>1-2</sup> ; Bartolozzi <sup>3</sup> ; Möller <sup>3</sup> ; Kobler <sup>3</sup> ; WeBel <sup>3</sup> ; Brand <sup>4</sup> ( <sup>1</sup> Fraunhofer ITWM; <sup>2</sup> Hochschule Kaiserslautern; <sup>3</sup> Fraunhofer LBF; <sup>4</sup> BPW Bergische Achsen)
12.15	Workflows für die virtuelle Absicherung von autonomen Nutzfahrzeugen in der Cloud	Bilgic Istoc (IPG Automotive)

## INNOVATIVE DEVELOPMENT AND PRODUCTION METHODS (2)

room 115

11.00	Truck Seat – Strategy for a Green Product	Paruchuri; Stuber (Grammer)
-	Lasttragende Leichtbau-Wasserstofftanks zur optimalen Bauraumausnutzung im Nutzfahrzeug	Motsch-Eichmann; Pfaff; Hausmann (Leibniz-Institut für Verbundwerkstoffe)
12.15	Functional Safety in the Development Process of Mobile Cranes	Schneider (Tadano Demag)

## ALTERNATIVE PROPULSION TECHNOLOGIES (2)

room 115

13.45	Die nächste Generation der Elektromobilität bei Daimler Truck	Lehmann (Daimler Truck)
-	Vergleich gemischtsaugender und luftansaugender Biopropan-Diesel Dual-Fuel Brennverfahren	Müller; Günthner (RPTU Kaiserslautern-Landau)
15.00	Practical and Customer-oriented electrification of agricultural tractors	Rajani; Reiter (John Deere)

# PROGRAM COMMITTEE

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*BPW Bergische Achsen, Wiehl*

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*RPTU Kaiserslautern-Landau*

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*Fraunhofer ITWM, Kaiserslautern*

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*TU Graz (A)*

Dr.-Ing. U. Faß  
*Volvo CE, Konz*

Prof. Dr.-Ing. D. Görges  
*RPTU Kaiserslautern-Landau*

Dr.-Ing. C. Göttlicher  
*Palfinger; Bergheim (A)*

Prof. Dr.-Ing. M. Günthner  
*RPTU Kaiserslautern-Landau*

T. Ille  
*MAN Truck & Bus, München*

Dr. S. Hammes  
*BOMAG, Boppard*

R. Kalmar  
*Fraunhofer IESE, Kaiserslautern*

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*Fraunhofer ITWM, Kaiserslautern*

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*Chalmers University of Technology, Gothenburg (S)*

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*John Deere, Kaiserslautern*

E. Schobesberger  
*Liebherr-EMtec, Kirchdorf*

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Dr.-Ing. J. Wieser  
*Tadano, Zweibrücken*

M. Wildhagen  
*SchmitzCargobull, Altenberge*

Prof. Dr. F. Will  
*TU Dresden*



**commercial vehicle alliance**  
kaiserslautern

Umbrella organization of:



Rheinland-Pfälzische  
Technische Universität  
Kaiserslautern  
Landau

Center for Commercial Vehicle Technology  
(ZNT)

RPTU Kaiserslautern-Landau



Commercial Vehicle Cluster -  
Nutzfahrzeuge GmbH (CVC)



High Performance Center Simulation and  
Software-Based Innovation -  
»Digital Commercial Vehicle Technology«  
Fraunhofer ITWM/Fraunhofer IESE

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